Building Complexity: Insights into Self-Organized Assembly of Microtubule-Based Architectures

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Successful completion of diverse cellular functions, such as mitosis, positioning organelles, and assembling cilia, depends on the proper assembly of microtubule-based structures. While essentially all of the proteins needed to assemble these structures are now known, we cannot explain how even simple features such as size and shape are determined. As steps toward filling this knowledge gap, there have been several recent efforts toward reconstituting, with purified proteins, the basic structural motifs that recur in diverse cytoskeletal arrays. We discuss these studies and highlight how they shed light on the self-organized assembly of complex and dynamic cytoskeleton-based cellular structures.

Introduction

Microtubules are polar polymers of αβ-tubulin heterodimers required for directional transport and micromechanical functions in eukaryotic cells. In dividing cells, a complex and dynamic array of microtubules, called the bipolar spindle, is needed to segregate chromosomes and position the cell-division plane (Glotzer, 2009; Wittmann et al., 2001). In nondividing cells, microtubules are needed for a wide range of processes, including positioning organelles (Carazo-Salas and Nurse, 2006), polarized growth (Wasteneys and Ambrose, 2009), migration (Kaverina and Straube, 2011; Watanabe et al., 2005), and the assembly of flagella and cilia (Ishikawa and Marshall, 2011). In differentiated cells, such as neurons, organized microtubule bundles provide tracks for the intracellular transport needed for axonal growth (Conde and Cáceres, 2009; Stiess and Bradke, 2011). Microtubules also contribute to the polarized secretion needed for axonal growth. For example, overlapping pairs of microtubules with antiparallel tracks for transport or cues to organize the cytoplasm or to generate force, it is crucial that these dynamic polymers are precisely organized.

Essentially all of the different microtubule-associated proteins (MAPs) needed to assemble microtubule-based structures have now been identified and can be divided into four groups. The first group consists of motor proteins (e.g., kinesins and dynein) that use the energy from ATP hydrolysis to step along microtubule tracks to transport cargo (Vale, 2003). The second group includes crosslinking proteins that align filaments with a specific geometry and stabilize structures (Bratman and Chang, 2008; Peterman and Scholey, 2009). The third set comprises proteins that modulate microtubule number. These include regulators of nucleation (Kollman et al., 2011; Lüders and Stearns, 2007) and enzymes that sever pre-existing filaments (Roll-Mecak and McNally, 2010; Sharp and Ross, 2012). The fourth group consists of regulators of dynamic instability, a characteristic property of microtubules that involves abrupt switch-like transitions between periods of assembly and disassembly from filament ends (Desai and Mitchison, 1997; Howard and Hyman, 2009). These proteins can regulate different parameters of dynamic instability, such as the rates of tubulin assembly, or the frequencies of catastrophe (i.e., the switching from assembly to disassembly) and rescue (i.e., the transitions from disassembly to growth). Different combinations of MAPs from these four groups somehow work together to assemble microtubule arrays involved in diverse cellular processes.

While the discovery of these MAPs represents major advances in the field, we still cannot explain how the size and shape of different microtubule-based architectures, whose dimensions are orders of magnitude greater than that of the molecules involved, are determined. It is also becoming clear that the rules that explain the assembly of large, multicomponent well-ordered structures, such as the ribosome, may not directly apply to the assembly of microtubule arrays, such as the bipolar spindle, as these structures can be highly dynamic and irregular in composition and molecular contacts. Therefore, while understanding the stereospecific interactions between the key molecular components is important, it is not sufficient to shed light on how the size or the shape of micron-scale microtubule arrays is determined. To answer these questions, we believe that an important step is to determine and characterize the smallest set of components needed to build key structural motifs, such as aligned microtubule bundles or asters, recurring in the diverse microtubule arrays needed for cellular function (Figure 1). A useful framework for the assembly of these structures is self-organization on the micron length scale (Mitchison, 1992; Nédélec et al., 2003). In such models, these dynamic architectures are believed to emerge from the activities of numerous proteins that follow simple rules and respond to local cues, which could be chemical or mechanical. Self-organization does not depend on a blueprint or a master organizer and is distinct from self-assembly as it requires continuous energy input.

A structural motif comprised of two aligned microtubules that overlap is found in several different arrays and contributes to the dynamic organization of the cytoplasm in at least two ways. First, it can generate forces to drive intracellular movement. For example, overlapping pairs of microtubules with antiparallel orientations can push centrosomes apart at the start of cell division (Tanenbaum and Medema, 2010; Wittmann et al., 2001). Second, these arrays can encode intracellular position. For example, the overlap region in an antiparallel array can recruit...
proteins to “mark” the midpoint between segregating anaphase chromosomes (Glotzer, 2009). Such marks are proposed to help position the site of cell cleavage. To carry out cellular functions with fidelity, the overall length and the overlap length of aligned microtubule bundles must be precisely controlled.

In this review, we highlight recent advances in our understanding of how size and shape of microtubule-based structures are determined. To frame our discussion of important recent findings relating to motor and nonmotor MAPs, we focus on the self-organized assembly of aligned bundles of two overlapping microtubules. The parameters that describe this motif are the overall end-to-end distance of the aligned microtubules and the overlap length between the two filaments. We discuss reconstitution studies with purified proteins and structural analyses that reveal how motor and nonmotor proteins set these parameters by regulating the relative position of two microtubules, the lengths of filaments, and the extent of filament overlap. We also discuss how these findings inform on the organization of the microtubule aster, another basic building block. Finally, we highlight some of the similarities and differences between prokaryotic and eukaryotic cytoskeletons.

Controlling the Relative Position of Two Microtubules

Can a two-component system, composed of microtubules and a crosslinking motor protein, align two microtubules such that the size of this simple motif is controlled? As it turns out, this is not the case. When two antiparallel microtubules are crosslinked by a motor protein, the relative displacement of the filaments will continue until the motor protein reaches the end of the track, and the overlap between the two microtubules will be lost (Figure 2A). This is exactly what is observed in total internal reflection fluorescence (TIRF) microscopy-based assays examining relative microtubule sliding by widely conserved kinesins required for eukaryotic cell division. Kinesin-5, the plus-end-directed motor needed for bipolar spindle assembly, and kinesin-14, the minus-end-directed motor needed to properly organize the two ends (called “poles”) of the bipolar spindle, have been shown to slide two antiparallel microtubules apart (Braun et al., 2009; Fink et al., 2009; Kapitein et al., 2005). However, the action of these proteins alone cannot keep microtubules aligned with different overlap lengths.

Analysis of two parallel microtubules crosslinked by a motor protein reveals that the filaments do not move relative to each other and that therefore, the size of this simple array cannot be modulated by protein activity (Figure 2B). Why is this? For kinesin-5, which is a homotetramer that crosslinks two microtubules by binding each filament with a pair of motor domains, the stepping of the motor domains toward the plus ends of each of the parallel filaments results in the motion of the kinesin itself but not in any relative movement of the microtubules (Figure 2B, inset in i). Parallel filaments do not move when crosslinked by kinesin-14, which uses a pair of motor domains to walk on one microtubule and a nonmotor domain to interact with the second filament. To crosslink two microtubules, kinesin-14 orients stochastically and its motor domains are equally likely to bind either of the two filaments. Therefore, as shown in inset ii of Figure 2B, the stepping of one kinesin-14 molecule toward the minus end of the lower filament opposes another kinesin-14 molecule stepping on the top filament, thereby preventing relative filament motion. While the ability of other motor proteins to slide apart parallel filaments still needs to be examined, the findings thus far indicate that another molecular component is
needed to stably align microtubule bundles and build a structure of fixed length.

In principle, the additional component needed to control the size of an aligned microtubule pair could be another motor protein. This minimal system would involve one motor protein that walks toward the microtubule plus end and another that walks toward the minus end. The antagonizing activities of these two different motor proteins could be balanced by tuning relative concentrations. Thus far, thorough experimental tests of this hypothesis have been carried out with the plus-end motor protein, kinesin-5 (pink) and the minus-end motor protein, kinesin-14 (Hentrich and Surrey, 2010; Tao et al., 2006). These experiments, as well as computer simulations, have led to the conclusion that a persistent balance of forces is not achieved by these two motors. Instead, bidirectional oscillations are observed in which microtubules move back and forth, frequently pausing between reversals of direction (Civelekoglu-Scholey et al., 2010; Hentrich and Surrey, 2010; Tao et al., 2006). The same behavior has also been observed with another pair of antagonistic motor proteins, kinesin-1 and dynein (Vale et al., 1992). To understand this phenomenon, one has to consider both the stochastic fluctuations in motor protein numbers during sliding and the force-dependent detachment of motors from microtubules. Briefly, when a balance in opposing activities is achieved, the numbers of motor proteins will fluctuate due to binding and unbinding kinetics (Figure 2C). If the number of plus-end-directed kinesins decreases, the force balance will tip and increase the dissociation of additional molecules of the same kinesin due to higher

Figure 2. Formation of Aligned Microtubule Bundles by Motor and Nonmotor Crosslinking Proteins

(A) Schematic shows how crosslinking and sliding of antiparallel microtubules (gray) by kinesin-5 (pink) can completely separate the two filaments. (B) Movement of kinesin-5 between two parallel microtubules does not result in relative displacement of the filaments. The inset shows the stepping of (i) kinesin-5 (pink) and (ii) kinesin-14 (blue) motor proteins on two parallel microtubules. (C) A model for bidirectional oscillations of antiparallel microtubules crosslinked by two antagonistic motor proteins (plus-end-directed motor protein, red; minus-end-directed motor protein, blue). (D) Proposed mechanism by which the nonmotor crosslinking protein, Ase1 (green), and the motor protein, kinesin-14 (blue), generate antiparallel microtubule overlap of fixed length.
opposing force. The filaments will thus move relative to each other, and eventually, reassociation of the plus-end-directed kinesin will be favored and the force balance will be restored (Figure 2C). However, this is only transient, as the same events will disrupt the balance and result in oscillations. Our current understanding of these systems indicates that a three-component system comprised of microtubules and opposing motor proteins is also not sufficient to generate aligned microtubules that have fixed overlap and overall length.

Another possible three-component system that can regulate the size of these basic building blocks is one comprised of microtubules, a motor protein, and a nonmotor crosslinking protein. Compared to motor proteins, nonmotor crosslinking proteins are a poorly understood class of MAPs. Recently, important roles for these proteins in the organization of overlapping microtubule arrays have been suggested from examining the PRC1/Ase1/MAP65 family of microtubule crosslinking proteins. These proteins play key roles in organizing microtubules in a variety of different cellular contexts, such as directing cell growth in plants, nuclear positioning in yeast, and cell division in all eukaryotes. Members of this protein family are characterized by their ability to selectively crosslink microtubules in an antiparallel orientation (Bieling et al., 2010; Janson et al., 2007; Kapitein et al., 2008; Subramanian et al., 2010; Gaillard et al., 2008).

Cellular studies of their function suggest that these proteins participate in the organization of antiparallel microtubules in conjunction with a number of different motor proteins. In particular, organization of interphase microtubule arrays in fission yeast has suggested a model in which Ase1, the fission yeast PRC1, counteracts kinesin-14’s activity to control microtubule overlap (Janson et al., 2007). Importantly, in vitro studies of this three-component system, comprised of microtubules, recombinant Ase1, and kinesin-14, are consistent with this model (Braun et al., 2011). Ase1, like other PRC1 homologs, binds with high affinity to antiparallel microtubule overlap regions. TIRF-imaging assays revealed that when kinesin-14 slides apart a pair of antiparallel microtubule overlap regions, the density of Ase1 in the overlap increases as overlap length decreases. The accumulated Ase1 opposes motor-protein-driven sliding and stalls the relative sliding of the two microtubules (Figure 2D). Under the experimental conditions of this study, stalling occurs when the ratio of Ase1 to kinesin-14 in the antiparallel overlap exceeds 4:1 (Braun et al., 2011). These findings indicate that a three-component system can align two microtubules such that the overlap length can be controlled by relative amounts of Ase1 and kinesin-14 in the overlap region. Once the overlap length is set, the end-to-end distance of the aligned filament array is simply determined by the lengths of the two microtubules and the overlap between them.

Is this a general mechanism for the organization of microtubule arrays by the PRC1 family of MAPs? The answer to this question appears to be no. In contrast to Ase1, when human PRC1-crosslinked antiparallel microtubules are moved apart by kinesin-5, PRC1 density in the overlap region does not increase as overlap length reduces. Instead, the two microtubules completely separate, as is observed with the motor protein alone (Subramanian et al., 2010). Why these differences are observed between the human and yeast homolog of PRC1 is an open question. It is possible that this is due to the multimerization of Ase1 under some conditions, a property not observed for PRC1 (Kapitein et al., 2008). Alternatively, Ase1/PRC1 crosslinks may respond differently when filaments are moved by the two different motor proteins, kinesin-5 and kinesin-14. While this needs to be examined further, it is possible that these differences are adaptations for Ase1/PRC1’s cellular functions. In budding yeast, the sliding of Ase1-crosslinked microtubules by kinesin-5 motors is required for the elongation of the antiparallel microtubules of the spindle at anaphase. Therefore, it may be advantageous for Ase1 to not act as a “brake” against kinesin-5 (Khmelinskii et al., 2009). However, in the formation of overlapping bundles in the interphase cells of fission yeast, the same nonmotor crosslinker is paired with kinesin-14, which it can effectively stall (Carazo-Salas and Nurse, 2006; Janson et al., 2007). PRC1/Ase1/MAP65 proteins also function together with other motor proteins, such as kinesin-6 (or Mklp1) (Fu et al., 2009; Gruneberg et al., 2006), kinesin-7 (or Cenp-E) (Kurasawa et al., 2004), kinesin-4 (or Kif4A) (Kurasawa et al., 2004; Zhu and Jiang, 2005). Interestingly, analysis of how PRC1 and kinesin-4 regulate the assembly of antiparallel arrays (see below) has revealed a very different mechanism than what has been proposed for Ase1 and kinesin-14. Additional studies will help unravel the different ways by which motor and nonmotor proteins can control the size of a basic structural motif comprised of two microtubules.

It is helpful to consider the biophysical basis of how a combination of motor and nonmotor proteins may control the relative sliding of microtubules to determine size. The magnitude of frictional forces due to a crosslinking nonmotor protein, as would be needed to oppose a kinesin that slides two microtubules apart, is proportional to (1) its frictional coefficient, (2) filament velocity, and (3) the number of molecules. The frictional coefficient is typically inversely proportional to the coefficient for one-dimensional (1D) diffusion of the MAP on the microtubule lattice. For human PRC1, estimates of frictional force based on measured diffusion coefficients suggest that over 100 PRC1 molecules are needed to counteract the force generated by kinesin-5 moving at ~20 nm/s. As the frictional force is proportional to velocity, its magnitude will decrease as the relative filament sliding velocity reduces (Bormuth et al., 2009). Therefore, to further slow down the sliding of crosslinked filaments, additional nonmotor molecules must somehow accumulate. Further, the extent to which a motor protein will slow down due to opposing force will depend on the motor protein’s “force-velocity” relationship. For example, the velocity of kinesin-5 is not greatly reduced over a wide range of opposing loads, while other kinesins, such as kinesin-1, exhibit steep dependencies in the same range (Svoboda and Block, 1994; Valentine et al., 2006). Consequently, all else being similar, kinesin-5 is less likely to stall compared to kinesin-1. While force generation by motor proteins has been carefully examined, the frictional forces generated by nonmotor proteins remain poorly characterized, and additional work is needed to understand how these proteins may function as brakes in the organization of microtubules into aligned bundles of fixed length.

Regulating Microtubule Length

Are the “slide-and-stall” mechanisms sufficient to control the length of simple microtubule-based motifs in cells? The in vitro
experiments discussed so far are typically performed with taxol-stabilized microtubules and do not take into consideration microtubule dynamics. Microtubules exhibit dynamic instability, and individual polymers continuously grow or shrink in the presence of GTP (Figure 3A) (Desai and Mitchison, 1997). Therefore, even when a stable overlap is achieved by crosslinking proteins, microtubule length will continuously fluctuate. This may also result in the separation of the two microtubules. It is therefore not surprising that the length of microtubule-based structures depends on proteins that regulate microtubule polymerization.

**Microtubule Destabilization by Motor Proteins**

While kinesins are best known for their function in transporting cargo along microtubules, widely conserved members of this superfamily directly regulate the depolymerization of the microtubule tracks, harnessing the energy from ATP hydrolysis to disassemble microtubules. Here we discuss insights into the functions of these atypical motor proteins that have come from studies of MCAK, a kinesin-13, and KiP3, the yeast kinesin-8, and how these proteins regulate microtubule dynamics.

Both of these proteins have important functions during cell division. Kinesin-13 plays a role in determining the size of microtubule-based structures and establishing proper chromosome-microtubule attachment in dividing cells (Wordeman, 2005). Kinesin-8 is required for proper chromosome alignment to the spindle equator during metaphase (Gardner et al., 2008; Su et al., 2011).

TIRF-microscopy analysis with recombinant proteins and dynamic microtubules shows that both kinesin-13 (Helenius et al., 2006; Hunter et al., 2003) and kinesin-8 (Gupta et al., 2006; Varga et al., 2006) accumulate at the ends of dynamic microtubules, where they increase catastrophe frequency (Figures 3B and 3C). How do these proteins find microtubule ends? It turns out that these motor proteins use two different mechanisms. Kinesin-8 walks to the plus end of a microtubule and specifically destabilizes this end (Figure 3C) (Gupta et al., 2006; Varga et al., 2006). In contrast, kinesin-13 finds microtubule ends by 1D diffusion along the filament lattice and can destabilize either end (Figure 3B) (Helenius et al., 2006; Hunter et al., 2003). Recently, Patronin and Microsphere protein 1 (MCRS1) have been identified as putative suppressors of kinesin-13 microtubule depolymerization activity at the microtubule minus end, thereby allowing control over kinesin-13’s microtubule-end specificity (Goodwin and Vale, 2010; Meunier and Vernos, 2011).

Interestingly, kinesin-8 can destabilize longer microtubules faster than it can shorter microtubules. How is this achieved? It has been shown that kinesin-8 is a processive motor protein with a low dissociation rate from microtubules (Varga et al., 2006). As a consequence, most of the kinesin-8 molecules that land on a microtubule have a high probability of getting to the end of that filament. Longer microtubules have more binding sites and will accumulate more kinesin-8 than shorter microtubules. Therefore, the plus ends of longer filaments will accumulate more kinesin-8. In current models, cooperative interactions between kinesin-8 molecules at microtubule ends physically “bump off” a kinesin-8 bound to a tubulin dimer to disassemble the filament (Varga et al., 2009) (Figure 3C). Therefore, more kinesin-8 molecules at the ends of longer filaments lead to faster disassembly of filaments.
What are the advantages of these different length-regulation mechanisms for the biological function of these destabilizing kinesins? Indiscriminate and fast depolymerization, as seen with kinesin-13, may be useful under conditions where extensive microtubule depletion is desired. This may be advantageous during mitosis for efficient depolymerization of microtubules that make improper attachments to chromosomes. Selective depolymerization of long microtubules, as seen with kinesin-8, is better suited for processes that require fine control over microtubule length, such as during the alignment of chromosomes at the equator of the metaphase spindle during mitosis.

Further insight into the function of these motor proteins has come from structural studies of kinesin-13. Electron micrographs of kinesin-13-bound microtubules show that in the presence of ATP analogs, the tight binding of these kinesins at microtubule ends results in a distortion of the microtubule protofilaments such that they curl and unravel (Desai et al., 1999; Moares et al., 2002). Cryo-electron microscopy studies have shown that depolymerizing microtubule ends are associated with increased curvature, which disrupts the lateral interaction between protofilaments (Hyman et al., 1995). Together, these structural studies suggest that disassembly of microtubules is induced by kinesin-13-dependent stabilization of curved protofilaments. A similar mechanism has been proposed for stathmin, a nonmotor microtubule-destabilizing protein (Belmont et al., 1996; Cassimeris, 2002). The crystal structure of the stathmin bound to tubulin shows that the tubulin dimer adopts a curved conformation in this complex (Gigant et al., 2000; Ravelli et al., 2004). Though kinesin-8 is also suggested to have an effect on microtubule ends similar to that of kinesin-13, the structural basis of microtubule depolymerization by kinesin-8 is poorly understood (Peters et al., 2010). Currently, it is unclear how the kinesin-8 motor domain distinguishes between tubulin in the middle of the microtubule, where it walks processively, and tubulin at filament ends, where it promotes destabilization. How cooperative interactions between kinesin-8 molecules at microtubule ends trigger destabilization must also be resolved through structural studies.

**Microtubule Growth by Nonmotor Microtubule-Associated Proteins**

The activities of microtubule-destabilizing motor proteins in cells are antagonized by nonmotor MAPs that increase microtubule length by promoting polymerization. The best understood among these are the evolutionarily conserved proteins, XMAP215 (Dist1/Stu2) and CLASP (Orbit/Stu1), which promote microtubule growth in a variety of biological contexts, as in the cases of directional growth in plants, cell polarization in neurons, microtubule growth in many cell types, other proteins that promote this reaction have also been identified. Among these is CRMP2, which has important roles in axonal growth in neurons but, unlike XMAP215 and CLASP, lacks TOG domains. In CRMP-2, the tubulin-binding domain adopts a fold seen in the metabolic enzyme dihydropyrimidinase (Stenmark et al., 2007). The tubulin-CRMP-2 complex is likely transported to the filament plus end by kinesin-1, where tubulin is transferred to the growing microtubule ends (Fukata et al., 2002; Kimura et al., 2005). It remains to be seen whether this occurs by the tubulin-binding domain discriminating between different tubulin structural forms. It is possible that an active transport process ensures a more efficient accumulation of CRMP2 and tubulin at microtubule ends compared to the diffusion-based processes that target the TOG-domain-containing proteins to microtubules. Microtubules undergoing dynamic instability can have broad length distributions that are modulated by MAPs (Gardner et al., 2010).

How are microtubule ends found by XMAP215 and CLASP? Analysis of the microtubule interactions of XMAP215 at the single-molecule level shows that it diffuses in 1D along the microtubule lattice (Brouhard et al., 2008). At the microtubule plus end, XMAP215 binds with high affinity and tracks the tip of the growing microtubule (Figure 3D). In this end-bound state, it catalyzes multiple (~25) rounds of tubulin addition to the microtubule end (Brouhard et al., 2008). In contrast to XMAP215, CLASP does not autonomously target microtubule ends. In vitro, it binds uniformly along the microtubule lattice (Al-Bassam et al., 2010). In cells, CLASP piggybacks on other microtubule-binding proteins to localize to distinct subsets of microtubules (Akhmanova et al., 2001; Bratman and Chang, 2008; Mimori-Kiyosue et al., 2005). When a depolymerizing microtubule end encounters a CLASP-bound region within the lattice, the probability increases that the filament will undergo a rescue event (Figure 3E).

How do these TOG-domain-containing proteins transfer tubulin to microtubule ends? Insights into this process have come from a recent crystal structure of one of the TOG domains (TOG1) from the yeast XMAP215 homolog, Stu2p, bound to z-tubulin (Ayaz et al., 2012). The structure shows that the TOG-domain-bound tubulin adopts a “curved” conformation in this complex. This structural form is adopted by tubulin heterodimers in solution or at filament ends, but not in the middle of the microtubule lattice (Hyman et al., 1995; Löwe et al., 2001; Ravelli et al., 2004). This suggests a model in which the basic amino-acid-rich domain aids the interaction of XMAP215 with the microtubule lattice. When this molecule encounters a microtubule end, one of the multiple TOG domains will bind the curved tubulin heterodimers in this region. This will place the other TOG domain, the one that is carrying the un polymerized tubulin, close to the growing end. Microtubule assembly will occur by “hand-off” of the TOG-domain-bound soluble tubulin to the filament tip (Figure 3D). Concomitant straightening of the lattice will promote the dissociation of XMAP215 for another round of tubulin addition. While the hand-off model is appealing, additional work is needed to obtain direct evidence for tubulin transfer.

While TOG domains are the major regulators of microtubule growth in many cell types, other proteins that promote this reaction have also been identified. Among these is CRMP2, which has important roles in axonal growth in neurons but, unlike XMAP215 and CLASP, lacks TOG domains. In CRMP-2, the tubulin-binding domain adopts a fold seen in the metabolic enzyme dihydropyrimidinase (Stenmark et al., 2007). The tubulin-CRMP-2 complex is likely transported to the filament plus end by kinesin-1, where tubulin is transferred to the growing microtubule ends (Fukata et al., 2002; Kimura et al., 2005). It remains to be seen whether this occurs by the tubulin-binding domain discriminating between different tubulin structural forms. It is possible that an active transport process ensures a more efficient accumulation of CRMP2 and tubulin at microtubule ends compared to the diffusion-based processes that target the TOG-domain-containing proteins to microtubules.
Regulating Microtubule Overlap Length

There have been important advances in our understanding of how the overlap length of two aligned microtubules can be precisely determined, independent of the end-to-end distance of the filaments. In particular, insights into this mechanism have come from analyzing antiparallel microtubule arrays involving the crosslinking protein PRC1. Cell biological studies have indicated that PRC1 and kinesin-4 (kif4A/Xklp2) work together to maintain the overlap length of the central spindle, the microtubule array that emerges after chromosome segregation. Recent structural studies have begun to explain how this crosslinking mechanism is likely to come from crystal sliding. Instead, PRC1 acts as a “tag” for the microtubule overlap region and recruits kinesin-4, a motor protein that regulates polymerization dynamics.

How is the regulation of microtubule overlap length achieved by these two MAPs? In vitro analysis of microtubule dynamics in the presence of kinesin-4 shows that it acts as a suppressor of growth and catastrophe. However, unlike the other regulators of microtubule dynamics, such as kinesin-8 or XMAP215, which act on single microtubules, the activity of kinesin-4 is confined by PRC1 to filament plus ends that are part of an antiparallel array. Kinesin-4 alone has weak microtubule binding affinity and is recruited by PRC1 to regions of overlapping antiparallel microtubules (Figure 4) (Bieling et al., 2010). The motor protein then walks processively to microtubule ends in the overlap region and acts as a suppressor of microtubule polymerization dynamics (Figure 4) (Bieling et al., 2010). The final steady-state length of antiparallel microtubule overlap in this system is dependent on kinesin-4 concentration and initial length of the overlap (Bieling et al., 2010). Longer overlap regions recruit more kinesin-4. This increases the probability that the motor protein will arrive at the plus ends of longer microtubules, for faster inhibition of filament dynamics. The overlap length of microtubules in this aligned array therefore acts as an antenna to regulate its own length. This is analogous to the length-dependent microtubule destabilization by kinesin-8 (Varga et al., 2006). The reconstitution of microtubule organization by PRC1 and kinesin-4 nicely demonstrates a biochemical mechanism by which lengths of antiparallel overlaps can be controlled by suppression of microtubule dynamics. However, in these experiments, relative microtubule sliding is restricted as the distal ends of the filament are attached to the surface of the coverslip. It will be of interest to examine how the length of antiparallel overlaps established by PRC1 and kinesin-4 is altered by relative sliding of the two microtubules by another motor protein. This is relevant in dividing cells, in which motor proteins (e.g., kinesin-6) are recruited to the antiparallel microtubule array generated by PRC1 and kinesin-4.

A crucial feature of this model is that PRC1 selectively tags the overlap region of pairs of aligned antiparallel microtubules. Recent structural studies have begun to explain how this selective microtubule crosslinking can be achieved. PRC1 is a modular protein with a helical N terminus that is responsible for dimerization, a central spectrin domain that mediates microtubule binding, and a C terminus Lys-Arg-rich predicted unstructured domain that enhances the microtubule binding affinity (Subramanian et al., 2010). Tomograms of pairs of microtubules crosslinked by PRC1 shows that the protein forms well-ordered rod-like striations connecting two microtubules that are 35 ± 2 nm apart. In contrast, PRC1 appears more flexible on single microtubules, with only the spectrin domain adopting a well-defined conformation (Subramanian et al., 2010). These observations lead to the current working model in which the microtubule-interacting spectrin domains of PRC1 decode filament polarity. While it is inherently a flexible molecule, PRC1 adopts a relatively rigid conformation when crosslinking two antiparallel microtubules. In this configuration, the relative orientation of the two spectrin domains is restricted such that antiparallel crosslinks are favored. Further insights into this crosslinking mechanism are likely to come from crystal
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Figure 5. Organization of Microtubules into an Aster

Model for aster formation by (A) the minus-end-directed crosslinking motor protein kinesin-14 and (B) the combined activity of the nonmotor protein NuMA (green), the plus-end-directed motor protein kinesin-5, and the minus-end-directed motor proteins dynein (red) and kinesin-14 (blue).

what is the minimum number of components needed to build an aster?

As it turns out, asters are among the easiest of structures to assemble in vitro. A two-component system comprised of a motor crosslinking protein and microtubules can generate asters (Hentrich and Surrey, 2010; Nédélec et al., 1997; Surrey et al., 2001). The formation of asters requires that a motor protein crosslinks and moves two microtubules relative to each other until their ends come together. At the ends of microtubules, the motor must stay bound so that the filaments remain connected (Figure 5A). One of the best examples of aster formation is an in vitro reconstitution study demonstrating that asters of steady-state size could spontaneously assemble in mixtures of dynamic microtubules and the minus-end-directed motor protein, kinesin-14 (Hentrich and Surrey, 2010; Surrey et al., 2001). Not all crosslinking motor proteins form asters. In the same experiment as above, it was observed that the plus-end-directed crosslinking motor protein, kinesin-5, does not form asters (Hentrich and Surrey, 2010). One reason for this observation may be the low microtubule-crosslinking efficiency of kinesin-5 (Hentrich and Surrey, 2010). Another possibility is the low velocity of kinesin-5, which could make it difficult for the protein to reach the end of a rapidly growing microtubule (Hentrich and Surrey, 2010). The average length of filaments in an aster will be determined by microtubule dynamics. What determines the relative orientation of two filaments in an aster? Though this is not yet experimentally verified, filament orientation in asters is likely to be determined by the properties of the crosslinking molecule, as in the case of aligned microtubules.

How do asters form in cells? Studies in cell-free mitotic extracts (Gaglio et al., 1996; Gaglio et al., 1995) have led to current models for how asters assemble in cells. Briefly, the minus-end-directed motor proteins, kinesin-14 and dynein, carry out the minus-end-directed transport to coalesce microtubule ends. The plus-end-directed motor protein, kinesin-5, partially opposes the minus-end-directed forces to prevent filament separation. The nonmotor protein NuMA, crosslinks microtubules minus ends and acts as a brake against filament separation. The crosslinking activity of NuMA is restricted to the vicinity of microtubule minus ends by interaction with dynein (Figure 5B) (Merdes et al., 1996, 2000). Thus far, the biochemical studies of this multicomponent system are incomplete, and we lack in vitro reconstitutions with purified components. In addition, the structural basis of microtubule crosslinking by NuMA and the geometry it imposes on microtubules that comprise the aster remain to be elucidated. However, studies so far suggest that the net minus-end-directed forces generated by motor proteins and the preferential minus-end crosslinking by a nonmotor MAP

structures of PRC1 dimers. These studies should also shed light on how PRC1 binds kinesin-4 so that the motor protein can step along microtubules within the overlap region.

A less appreciated aspect of how motor and nonmotor MAPs crosslink microtubules is the role of interfilament spacing. Clues that this parameter is important come from studies of actomyosin networks in the vertebrate muscle showing that force generation during contraction is impacted by interfilament spacing (Matsubara et al., 1984). Measurements of uniform interfilament spacing indicate that this parameter can vary significantly between different microtubule arrays. For example, insect cells expressing the dendritic crosslinking protein, MAP2, show an intermicrotubule spacing of 61.7 ± 9.0 nm, whereas this distance in the axonal crosslinking protein, Tau, is 19.8 ± 4.1 (Chen et al., 1992). It is unclear how different motor proteins, whose lengths can also vary, slide these crosslinked arrays. For example, kinesin-5 is a 90-nm-long dumbbell-shaped tetramer and kinesin-4 is a 120-nm-long dimer (Kashina et al., 1996; Sekine et al., 1994). Both of these proteins are able to slide the microtubules crosslinked by PRC1, which are spaced ~35 nm apart.

How are proteins of widely different molecular size accommodated in a microtubule array? Given the high persistence length of microtubules, the probability of local filament deformations is low (Gittes et al., 1993). We favor the model in which one crosslinker dictates the intermicrotubule spacing. The network then acts as a “molecular sieve” that selectively excludes crosslinkers that cannot be accommodated based on size. Motor proteins and MAPs that do bind may need to adopt a particular crosslinking conformation. This could alter their association kinetics or force generation. Thus, by controlling the localization and activity of different proteins, the structure of the crosslinked filament network may regulate its organization to form structures of defined size and shape.

Implications for Aster Formation

Another recurring motif in microtubule-based structures is an aster. Similar to the antiparallel arrays, asters act as force generators and provide spatial cues in the cytoplasm. For example, astral microtubules play important roles in processes such as directed cell migration (Watanabe et al., 2005) and embryonic nuclear positioning (Morris, 2003; Wühr et al., 2009). An aster is formed when microtubules intersect at their ends instead of aligning parallel to each other. This structural motif can be defined by the length and the angular density of the filaments. This raises the question,

First, what is an aster?
are important factors in determining the shape of this structural motif and keeping the microtubules from becoming aligned as a bundle.

Filament Organization in Prokaryotic Cytoskeletal Networks

Cytoskeletal filaments, once considered to be hallmarks of eukaryotic cells, are also present in prokaryotes. These prokaryotic filaments play important roles in determining cell shape (Margolin, 2009; Shaevitz and Gitai, 2010), accurate segregation of plasmid DNA (Gerdes et al., 2010; Salje et al., 2010), and positioning of the cell-division plane (Caben and Jacobs-Wagner, 2010; Erickson et al., 2010). As in the case of microtubule-based architectures, these functions require precise organization of these filaments into structures of specific shape and length. A major difference between the two systems is that motor proteins have not yet been identified in any prokaryotic cells. Thus, filament organization must be driven entirely by crosslinking and regulation of filament length. Here we briefly summarize the role of filament bundling and dynamics in the proper assembly of cytoskeletal structures formed by the prokaryotic proteins FtsZ and ParM.

Similar to microtubules, crosslinking of prokaryotic filaments is likely to be important for their organization into different structures. A prominent example is the FtsZ ring. FtsZ is a structural homolog of tubulin that polymerizes to form filaments (Adams and Errington, 2009; Erickson et al., 2010). During cell division, FtsZ filaments are bundled to form a ring in the middle of dividing rod-shaped bacterial cells. This structure has been proposed to provide positional cues and generate forces during cell fission (Erickson et al., 2010). While FtsZ filaments appear to be capable of organizing into bundles on their own, a group of proteins, referred to as the Z-associated proteins (ZapA-D), have been identified as stabilizers of FtsZ bundles in cells (Adams and Errington, 2009; Kirkpatrick and Viollier, 2011). At least one of these proteins, ZapA, has been proposed to stabilize the Z-ring by crosslinking FtsZ filaments (Gueiros-Filho and Losick, 2002). It is postulated that positively charged regions in oligomeric ZapA could interact with the acidic C-terminal tail of FtsZ to form crosslinks in a manner reminiscent of interactions between microtubule and nonmotor proteins (Low et al., 2004). Therefore, the ZapA proteins may have functions that are analogous to those of microtubule crosslinking proteins. How the length of FtsZ filaments and their relative placement in the ring is determined remains unknown.

As with microtubules, the formation of structures of precise length will require the regulation of prokaryotic filament dynamics. Remarkably, in vitro reconstitution shows that filaments of the actin homolog ParM undergo dynamic instability similar to that observed for microtubules (Garner et al., 2004). These dynamics are harnessed for DNA capture and force generation for plasmid segregation in a manner reminiscent of the mitotic spindle. This process was recapitulated in an impressive in vitro reconstitution experiment with three components: dynamic ParM filaments; DNA containing the centromere-like site, parC; and ParR, which is a parC-binding protein. In current models, the ParR-parC nucleoprotein complex acts as a regulator of parM dynamics. When the dynamically unstable ParM filament is captured by the ParR-parC complex on plasmid DNA, the filaments are stabilized against catastrophe. This promotes ParM elongation, which in turn provides the pushing force for plasmid segregation (Garner et al., 2007). Therefore, as seen in eukaryotes, precise length control of the ParM filament can be achieved by using a regulatory protein to tune its intrinsic dynamics.

There have also been important advances in examining the components of the prokaryotic cytoskeleton at the structural level. The crystal structure of the ParR-DNA nucleoprotein complex and electron micrographs of ParM bound to ParR/parC have been obtained (Salje et al., 2010). These structural studies suggest a model in which both ends of ParM are effectively capped by the large solenoid-shaped ParR to reduce the rate of catastrophe while still allowing for monomer addition at the filament ends. The organization of FtsZ bundles is much less well understood. Electron cryotomographic reconstructions of dividing Caulobacter cells suggest that the Z-ring is made of short, curved filaments (Erickson et al., 2010). How these filaments are structurally interconnected by the Zap-proteins is not known. Biophysical analysis of the interactions of these proteins with the FtsZ filament, as well as high-resolution structural analysis of the crosslinks formed, will shed light on how the architecture of the Z-ring is determined.

Future Outlook

Elucidating the mechanisms of the self-organized assembly of microtubule-based structures requires an understanding of the properties of proteins involved, the reactions they participate in, and the final structure that emerges. As summarized in this Review, significant progress has been made in understanding the formation of some of the basic building blocks, such as a pair of antiparallel microtubules or an aster, that recur in the wide range of microtubule-based structures needed for cellular function. The next step is to extend these analyses to less understood structural motifs, such as the parallel microtubule bundles in axons or the mixed-polarity arrays in dendrites. Another major gap in our understanding of the formation of microtubule structures is how the filament number in these different arrays is controlled. We believe that visualization of microtubule nucleation in real time is the breakthrough needed. Together, these studies will reveal how not only the shape and length, but also the number of filaments, are controlled in the formation of microtubule-based structures.

During development and cell division, the formation of microtubule-based structures is tightly regulated by signaling molecules such as kinases and phosphatases. While significant advances have been made in the biochemical and structural analysis of motor proteins and MAPs, an understanding of the roles of signaling molecules in the formation of microtubule-based structures has largely been restricted to cell biological analysis. Yet even in the formation of a simple antiparallel bundle, kinases play critical roles. For example, during cell division, the mitotic kinase, Plk1 (polo-like kinase-1), is recruited to the antiparallel microtubule bundles. On these microtubule arrays, the interaction between PRC1 and Plk1 alters both the kinase activity of Plk1 and the microtubule binding of PRC1 (Hu et al., 2012; Neef et al., 2007). How such crosstalk between signaling and mechanical processes impacts the formation of microtubule-based structures of precise length...
needs to be addressed by in vitro reconstitution and structural methods.

In addition to motor proteins, nonmotor MAPs, and signaling molecules, the size of microtubule assemblies is likely to be controlled by tubulin posttranslational modifications. A diverse set of modifications, such as acetylation, detyrosination, polyglutamylation, and polyglycylation of αβ-tubulin, have been proposed to act as a “code” for the recruitment and activity of microtubule-binding proteins (Janke and Bulinski, 2011; Verhey and Gaertig, 2007). For example, it is suggested that detyrosination decreases the depolymerization activity of kinesin-13 (Peris et al., 2009). However, for the majority of modifications, their role in microtubule organization remains unclear due to the difficulty in obtaining homogeneously modified tubulin for biochemical and biophysical studies. With recent advances in both the expression of recombinant tubulin (Drummond et al., 2011; Johnson et al., 2011) and strategies for incorporating modified amino acids into proteins (Davis and Chin, 2012; Foley and Burkart, 2007; Vila-Perelló and Muir, 2010), the stage is now set for elucidating the role of tubulin posttranslational modification in the formation of microtubule arrays of specific size and shape.

Conclusions

The elaborate micron-scale microtubule-based architectures that assemble in cells function with remarkable fidelity. We have just begun to understand the molecular mechanisms that set the size and shape of the elementary motifs frequently found in diverse cytoskeletal structures. This is an important step toward deciphering how these arrays assemble and actually function. Complex nanoscale DNA-based motifs can now be built using relatively simple rules and components (Tørring et al., 2011). We are optimistic that like DNA origami, microtubule origami will soon be possible to allow synthesis of dynamic structures that can carry out complex cellular functions.

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